

AN ENERGY STORAGE SYSTEM

Billy H. Easter
School of Electrical Engineering
Oklahoma State University
Stillwater, Oklahoma

AN INTRODUCTION TO THE PROBLEM

Part of Oklahoma State University's program of energy storage research in the School of Electrical Engineering involves the use of unconventional energy sources such as wind and sunlight.¹ This energy must be used when available or stored until needed. Since the energy supply and demand are usually independent, some type of storage is needed to act as a buffer to match the two.² The storage system currently under study uses an electrolysis cell to convert electrical energy into hydrogen and oxygen under high pressure and stores them until they are used either in a fuel cell or in an internal combustion engine or steam turbo-generator.^{5,6,7}

Two slightly different power system configurations are prominent in our research efforts. For small systems the design is kept simple; for the larger systems the efficiency of operation becomes important enough to warrant additional switching and control devices. The two situations to be modeled using GPSS are the simple case shown in Figure 1-(A) wherein all energy passes through storage and the more complex situation shown in Figure 1-(B) wherein a direct path exists between the generator and the load in parallel with the storage system. The objective of the simulation is both to provide design information and to provide information for the economic optimization of the systems.

PHYSICAL COMPONENTS OF THE SYSTEM

A description of the system's physical components will aid in understanding the simulation diagrams.

Wind

GPSS is ideal for dealing with wind or solar phenomena because of their obvious statistical nature. This is indicated by Figure 2 which is a plot of the hourly readings of wind velocity at Will Rogers Airport in Oklahoma City for January of 1962. According to a report from Stanford University the gustiness of the wind depends upon the surrounding obstructions.³ Thus, a random number generator and an error function curve, the distribution function for the normal curve, with the properly chosen standard deviation are all that are needed to simulate the variations about the average (hourly) readings.⁴

Component Transfer Characteristics

The wide range of input power causes the actual

generator efficiency to vary because of varying speeds and fixed losses. The efficiency also varies because of the finite time needed for the wind-intercept device and generator to respond to gusts. The GPSS functions are readily adapted to simulate these two effects by two different functions. Figure 3 is an example of a function showing generator efficiency versus power input and Figure 4 shows percent effective wind velocity versus wind gust percent.

Transmission efficiency from the generator to its loads can be a constant or it can be represented by a function. A GPSS function is well suited to characterize the nonlinear electrolysis cell action when it acts as a load.

Storage

After electrolysis the gases are stored in high-pressure tanks. The GPSS entity of storage is ideally suited to this simulation. Energy leakage from the tanks is simulated by removing units periodically from storage. The number of units removed is a function of the total storage, i.e., the pressure in the tank.

Reconversion Device Characteristics

At this point the physical problems diverge but the simulation techniques do not. The reconversion characteristic functions for a fuel cell and a steam turbogenerator will differ but the result in each case will be electrical energy for some electrical load. The simulation pattern for the two cases is the same.

ATTRIBUTES OF GPSS USED

While this simulation may not use the strongest feature of GPSS, i.e., queueing theory, it does find other attributes of GPSS to be highly desirable. The gathering of tabular data, the optional printout of savevalue data as desired, and the use of list functions are among these highly useful characteristics of GPSS. Also, the fact that component efficiencies may be functions rather than constants adds much realism to the simulation.

The simpler system is simulated by the program diagrammed in Figure 5, and the more comprehensive system is diagrammed in Figure 6. The inputs necessary are functions describing available energy versus time, load demand versus time, system efficiencies and definitions of variables. See Figure 7. (Function 1 is given for only one day because of space limitations but the other listings are presented as actually used in one of the

simulation runs.)

REFERENCE

OBJECTIVES OF PARTICULAR PROGRAM TECHNIQUES USED

Tabulating Data

In choosing generator ratings, wind-intercept areas, electrolysis cell or fuel cell ratings, and storage capacities, the designer needs to know as much as is practical about the utilization of each of these components. Thus power flow through each element is tabulated for study by the designer. The GPSS tables are ideally suited for providing the answers to such questions as: Is it economically sound to attempt to extract the peak energy from the wind gusts or will it be more economical to build a larger propeller and a smaller generator and thereby discard the peak energies?

Print Routines

In order to maintain a time relationship along with the statistical data, some very versatile print routines have been devised. The desired data are stored in savevalue locations and printed out at predetermined times. The routines allow such variations as printing the hourly data for every Friday (or Monday, etc.), printing data for only the month of July, or perhaps printing the data at 6:00 a.m. at the beginning of each day instead of having to print all the data for each .1 hour. Figure 8 is a plot of the total energy stored at 6:00 a.m. of each day for 3 months.

List Functions

Because of the nature of the look-up routines for continuous or discrete functions, their use becomes prohibitively time consuming for large amounts of data. Thus, list functions which simply use the data points in order are used whenever large amounts of data are needed.

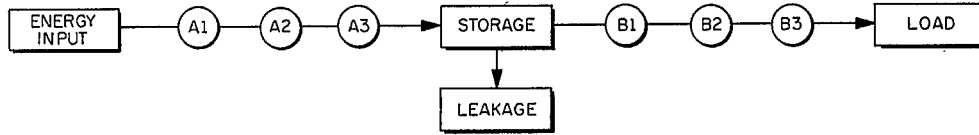
CONCLUSIONS

Figure 9 is a composite plot of the tabulated data for the instantaneous wind power, the instantaneous generator output, and the excess power sent to storage during a 3-month simulation. Similar data are tabulated for power transmitted directly to the load and power demand from storage systems.

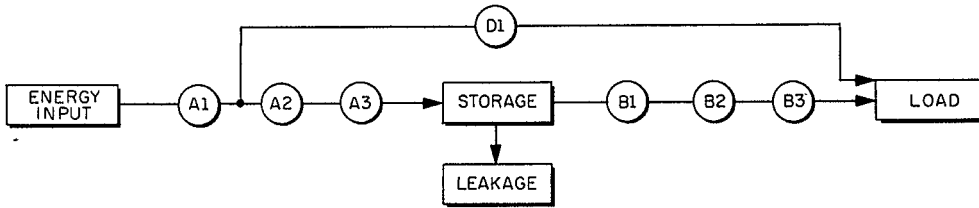
The next step is the using of this tool in developing design criteria for optimizing various variables of the system. Current projects in our laboratories include wind interrupt devices, electrolysis and fuel cells operating in stacks, and high pressure gas storage.^{4,6} From these projects should come the appropriate transfer functions needed by this program. This program will then be coupled with an optimization program for use in designing actual systems.

1. Proceedings of the United Nations Conference on New Sources of Energy, Seven Volumes, (Conference held in Rome in 1961), United Nations, New York, 1964.
2. Energy Storage - Key to Our Economic Future, Brochure presented by the Office of Engineering Research, Oklahoma State University, Stillwater, Oklahoma, 1963.
3. Merchant, David H., Stochastic Model of Wind Gusts, Ph.D. Thesis, Stanford University, 1965.
4. Gibson, LeRoy A., Wind Analysis in Relation to the Development of Wind Power, Ph.D. Thesis, Oklahoma State University, 1968.
5. Bruckner, Arthur II, A System for the Economic Analysis of Balanced Energy Conversion and Storage Systems, Ph.D. Thesis, Oklahoma State University, 1967.
6. Energy Conversion and Storage Research, Annual Report, School of Electrical Engineering, Oklahoma State University, 1968.
7. Bruckner, Arthur II, Fabrycky, W. J., and Shamblin, James E., "Economic Optimization of Energy Conversion with Storage", IEEE Spectrum, April, 1968.

○ - COMPONENT TRANSFER FUNCTIONS.



(a) BLOCK DIAGRAM OF SIMPLE SYSTEM



(b) BLOCK DIAGRAM OF COMPLEX SYSTEM

Figure 1. Block Diagrams of Systems.

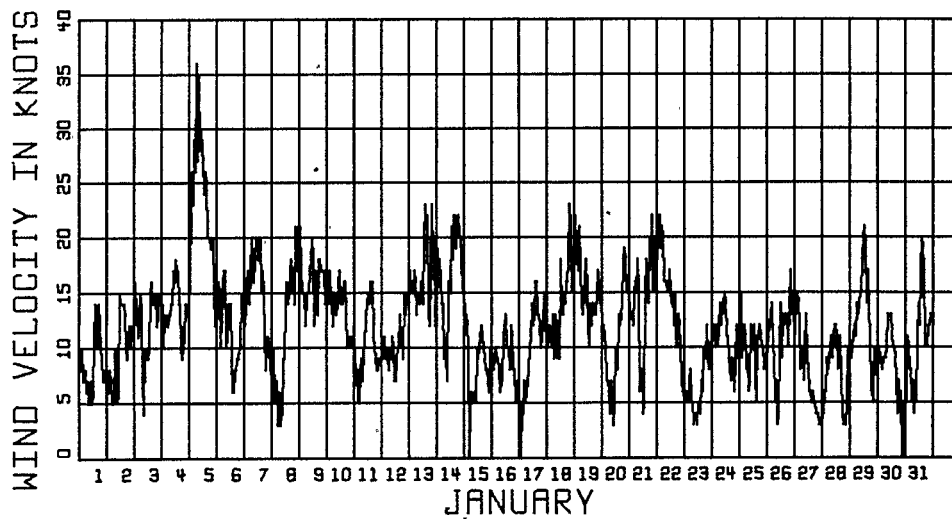


Figure 2. Wind Velocity for January of 1962 at Will Rogers Airport in Oklahoma City.

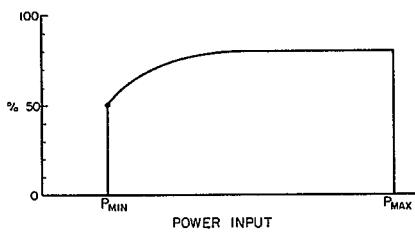


Figure 3. Generator Efficiency versus Power Input.

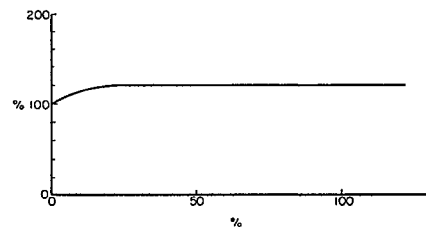


Figure 4. Percent Effective Wind Velocity versus Wind Gust Percent.

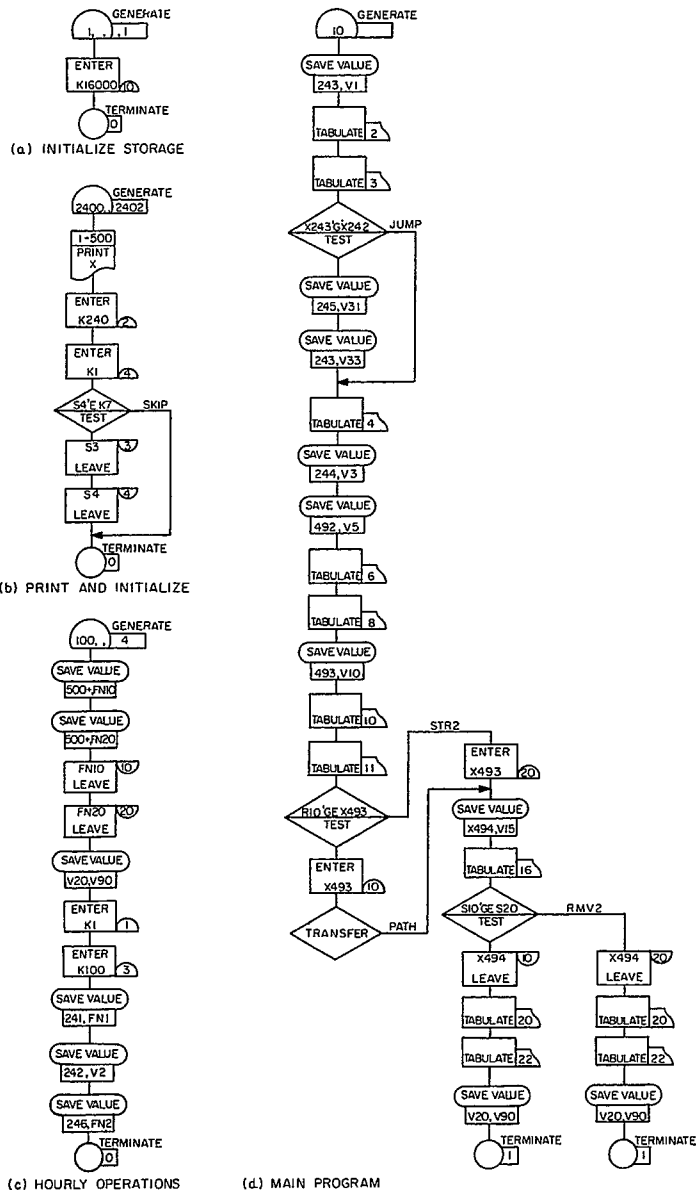


Figure 5. GPSS Diagram for Simple System.

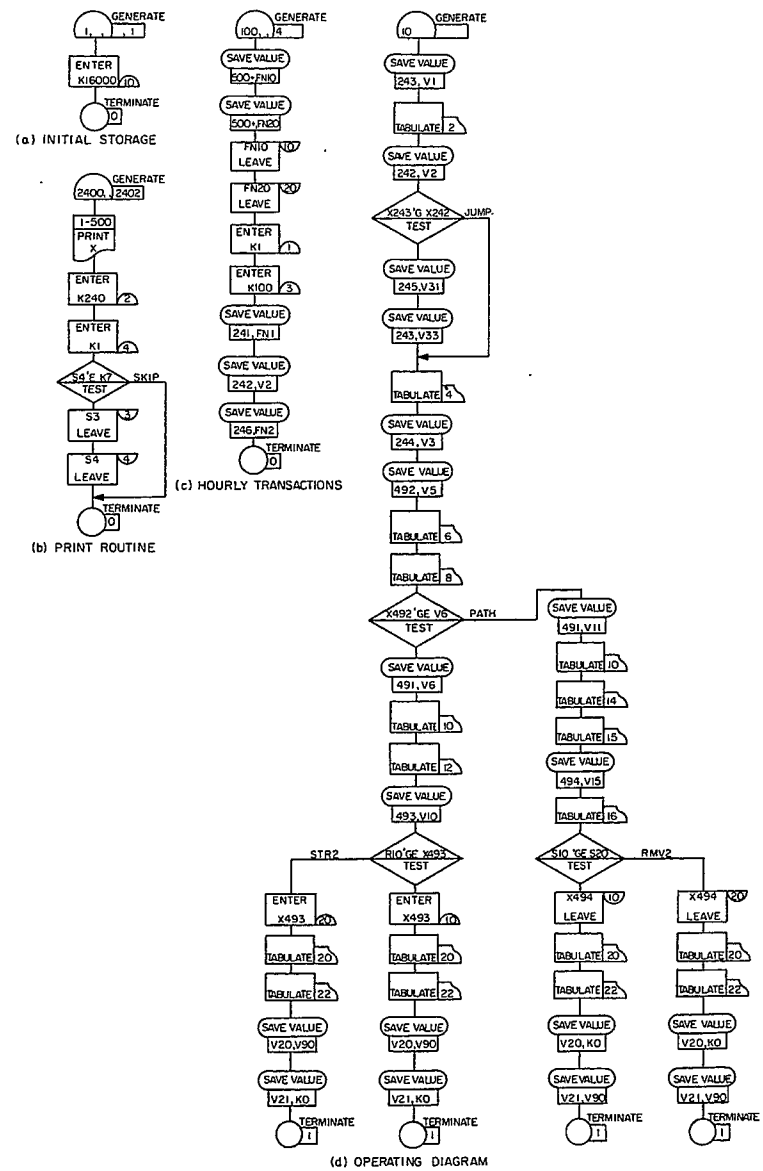


Figure 6. GPSS Diagram for Complex System.

```

1 FUNCTION S1,L24 WIND VELOCITY DATA
  9.0      8.0      10.0     7.0      7.0      8.0
  6.0      7.0      5.0      5.0      7.0      5.0
  6.0      11.0     14.0     11.0     10.0     14.0
  12.0     10.0     9.0      7.0      8.0      7.0
2 FUNCTION S3,D23 ENERGY DEMAND CURVE
  700      0 1200    500 1300    0 1800    500 3100    0 3600    500
 3700      0 4200    500 5500    0 6000    500 6100    0 6600    500
 7900      0 8400    500 8500    0 9000    500 10300   0 10800   500
10900      0 11400   500 12700   0 13200   500 16800   0
10 FUNCTION S10,D18 ENERGY LEAKAGE FUNCTION
  0 0 2000 1 4000 2 6000 3 8000 4 10000 5
12000 6 14000 7 16000 8 18000 9 20000 10 22000 11
24000 12 26000 13 28000 14 30000 15 32000 16 34000 17
20 FUNCTION S20,D18 ENERGY LEAKAGE FUNCTION
  0 0 2000 1 4000 2 6000 3 8000 4 10000 5
12000 6 14000 7 16000 8 18000 9 20000 10 22000 11
24000 12 26000 13 28000 14 30000 15 32000 16 34000 17
24 FUNCTION RN1,C15 ERROR FUNCTION CURVE, SIGMA = 0.2
  0 0 .001 40 .006 50 .023 60 .067 70 .159 80
.308 90 .500 100 .692 110 .841 120 .933 130 .977 140
.994 150 .999 160 1.0000200
30 FUNCTION X244,C6 GENERATOR EFFICIENCY CURVE
 342 0 343 172 3000 1800 50000 35000 20000016000099999800000
31 FUNCTION X245,C6 GUST EXTRACTION EFFICIENCY CURVE
 0 100 10 100 20 95 30 75 50 35 200 20
1 VARIABLE FN24*X241 SIMULATE GUST
2 VARIABLE X241*K100 SCALE AVERAGE VELOCITY
3 VARIABLE X243*X243/K1000*X243/K1000 CUBE EFFECTIVE INST VEL
5 VARIABLE FN30*15/100 GENERATOR EFFICIENCY AND SCALE FACTOR
6 VARIABLE X246*100/95 CALCULATE DIRECT LOAD DEMAND
7 VARIABLE X492-V6 CALC EXCESS ENERGY
8 VARIABLE V7*98/100 EXCESS ENERGY TRANSMITTED TO FUEL CELL
9 VARIABLE V8*65/100 EXCESS ENERGY CONVERTED TO GAS
10 VARIABLE V9/K10 DIVIDE BY 10
11 VARIABLE X492*99/100 CALC DIRECT ENERGY TO LOAD
12 VARIABLE X246-V11 CALCULATE EXCESS LOAD DEMAND
13 VARIABLE V12*100/100 B3 EFFICIENCY
14 VARIABLE V13*100/96 B2 EFFICIENCY
15 VARIABLE V14/K10 B1 EFFICIENCY AND DIVIDE BY 10
20 VARIABLE C1/10-S2 CALCULATE LOWER SAVEVALUE ADDRESS
21 VARIABLE C1/10-S2+K250 CALCULATE UPPER SAVEVALUE ADDRESS
31 VARIABLE X243/X241-K100 CALC GUST PERCENT
32 VARIABLE FN31*X245/K100+K100 CALC EFFECTIVE WIND VEL PERCENT
33 VARIABLE V32*X242/K100 CALC EFFECTIVE WIND VELOCITY
90 VARIABLE S10+S20 CALC TOTAL STORAGE
2 TABLE X243,0,100,102 INST WIND VEL IN TBL 2
3 TABLE V3,0,100,502 INST WIND PWR IN TBL 3
4 TABLE X243,0,100,72 INST USEABLE VEL IN TBL 4
6 TABLE X492,0,1000,402 GEN OUTPUT IN TBL 6
8 TABLE X492,0,100,102 GEN OUTPUT EXPANDED IN TBL 8
10 TABLE X491,0,100,22 DIRECT TRANS TO LOAD IN TBL 10
12 TABLE V7,0,20,502 EXCESS ENERGY IN TBL 12
14 TABLE V12,0,20,102 EXCESS LOAD DEMAND IN TBL 14
15 TABLE V14,0,10,202 STORAGE ENERGY OUTPUT IN TBL 15
16 TABLE X494,0,1,202 ENERGY FROM STORAGE IN TBL 16
20 TABLE S10,0,100,332 INSTANTANEOUS CONTENTS OF STORAGE
22 TABLE S20,0,100,332 INSTANTANEOUS CONTENTS OF STORAGE

```

Figure 7. Listing of Functions and Definitions of Variables and Tables.

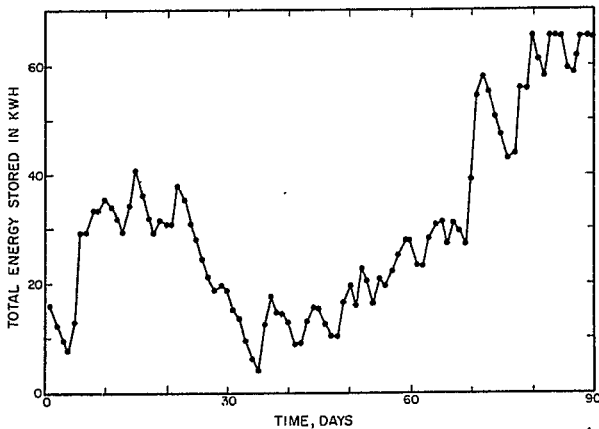


Figure 8. Total Energy Stored at 6:00 a.m. of Each Day.

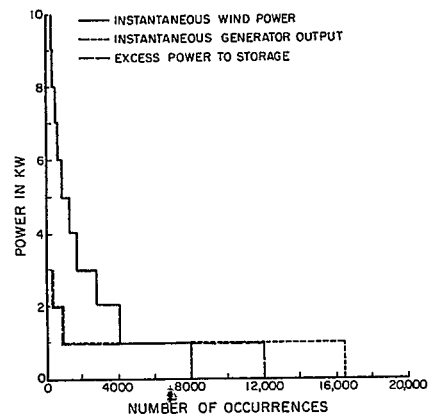


Figure 9. Composite Tabular Data.